A Practical Introduction to Numerical Methods for Materials Scientists and Engineers

David J. Keffer Professor of Materials Science & Engineering University of Tennessee Knoxville, TN

Copyright © 2013 David J. Keffer All rights reserved.

First Edition

ISBN-13:

This book is dedicated to my colleagues in the Materials Science & Engineering Department at the University of Tennessee, Knoxville, who provided a good home in which this book could be written.

Preface

We live in a world where our time is limited. As materials scientists and engineers, we fulfill the role of problem-solvers in society. Our success in this endeavor depends upon our ability to solve a particular problem within a given amount of time, which in turns depends upon our familiarity with and access to the standard tools of the trade. A rudimentary knowledge of the tools may allow us to provide a crude solution, whereas a more thorough knowledge of the tools may allow us to generate a more elegant and satisfying solution.

Today, many of the problems posed to materials scientists and engineers involve a computational component. Thus the analysis of a problem can be broken down into problem formulation and problem solution. Problem formulation requires creativity to construct a framework in which the material issue under investigation can be property understood. Problem formulation is also the most crucial step because through the formulation of the model we dictate the physics present in the model. If an important element is omitted in this step, the solution of the model either will not provide any insight into the problem at hand or worse yet provide erroneous guidance. Problem formulation is also the most exciting part of any investigation because our imagination can run wild at this point, leading us to ingenious approaches that not only solve the problem but help us to establish the reputation for creativity and excellence toward which we strive.

However, the formulation of the model must be followed by solution of the model. Today, there are standard tools for solving virtually any variety of mathematical equation, due to the cumulative labors of previous generations of mathematicians and computer scientists. With a working familiarity of these tools, the solution of most models should be simply a matter of methodical routine. While it is true that there is the opportunity to invoke our creativity in the solution of more advanced materials problems requiring specialized numerical techniques, there remains a broad swath of materials problems that can be routinely solved using a relatively small toolbox of standard numerical techniques.

There is the opportunity for great empowerment of the student with this approach. What we hope to avoid is a situation where the rigor in the formulation of the model is sacrificed in order to achieve a mathematically simpler expression, which can be solved with a very limited set of tools. What we hope to achieve is a situation where the formulation proceeds without regard for the ease of numerical solution. Once the model is rigorously formulated, the appropriate numerical solution is then identified. Thus the science guides the numerical techniques, rather than the other way around.

The philosophy espoused in this book is to equip the student with a compact but broadly applicable set of practical problem-solving tools such that the student emerges at the end of the course with the belief, "If I can write the model, I can solve the model."

Summary of the Contents of this Book

This book covers:

- numerical differentiation
- numerical integration
- solution of algebraic equations
 - o systems of linear algebraic equations
 - eigenanalysis
 - multivariate linear regression
 - o non-linear algebraic equations
 - single nonlinear algebraic equations
 - systems of nonlinear algebraic equations
 - optimization
- solution of ordinary differential equations
 - o single nonlinear ordinary differential equations
 - o systems of nonlinear ordinary differential equations
 - initial value problems
 - boundary value problems

This book does not cover:

- solution of partial differential equations
- solution of integral equations
- signal filtering, including Fourier transforms
- countless other more advanced numerical topics

Table of Contents

Preface	iv
Summary of the Contents of this Book	v
Table of Contents	vi
List of Subroutines	ix
Chapter 1. Linear Algebra	1
1.1. Introduction	1
1.2. Linearity	1
1.3. Matrix Notation	3
1.4. The Determinant and Inverse	5
1.5. Elementary Row Operations	7
1.6. Rank and Row Echelon Form	10
1.7. Existence and Uniqueness of a Solution	14
1.8. Eigenanalysis	20
1.9. Summary of Logically Equivalent Statements	29
1.10. Summary of MATLAB Commands	30
1.11. Problems	31
Chapter 2. Regression	32
2.1. Introduction	32
2.2. Single Variable Linear Regression	32
2.3. The Variance of the Regression Coefficients	33
2.4. Multivariate Linear Regression	36
2.5. Polynomial Regression	38
2.6 Linearization of Equations	38
2.7. Confidence Intervals	39
2.8. Regression Subroutines	41

2.9. Problems	46
Chapter 3. Numerical Differentiation	47
3.1. Introduction	47
3.2. Taylor Series Expansions	47
3.3. Finite Difference Formulae	48
3.4. Approximations for Partial Derivatives	51
3.5. Noise	52
3.6. Problems	55
Chapter 4. Solution of a Single Nonlinear Algebraic Equation	56
4.1. Introduction	56
4.2. Iterative Solutions and Convergence	56
4.3. Successive Approximations	57
4.4. Bisection Method of Rootfinding	59
4.5. Single Variable Newton-Raphson	61
4.6. Newton-Raphson with Numerical Derivatives	64
4.7. Solution in MATLAB	65
4.8. Existence and Uniqueness of Solutions	67
4.9. Rootfinding Subroutines	70
4.10. Problems	74
Chapter 5. Solution of a System of Nonlinear Algebraic Equations	75
5.1. Introduction	75
5.2. Multivariate Newton-Raphson Method	75
5.3. Multivariate Newton-Raphson Method with Numerical Derivatives	82
5.4. Subroutine Codes	83
5.5. Problems	85
Chapter 6. Numerical Integration	86
6.1. Introduction	86
6.2. Trapezoidal Rule	86
6.2. Second-Order Simpson's Rule	88
6.3. Higher Order Simpson's Rules	91
6.5. Quadrature	91
6.6. Example	92

6.7. Multidimensional Integrals	95
6.8. Subroutine Codes	98
6.9. Problems	103
Chapter 7. Solution of Ordinary Differential Equations	104
7.1. Introduction	104
7.2. Initial Value Problems	104
7.3. Euler Method	105
7.4. Classical Fourth-Order Runge-Kutta Method	107
7.5. Application to Systems of Ordinary Differential Equations	108
7.6. Higher-Order ODEs	110
7.7. Boundary Value Problems	111
7.8. Subroutine Codes	112
7.9. Problems	119
Chapter 8. Optimization	120
8.1. Introduction	120
8.2. Optimization vs Root-finding in One-Dimension	120
8.4. Other One Dimensional Optimization Techniques	123
8.5. Multivariate Nonlinear Optimization	124
8.6. Optimization vs Root-finding in Multiple Dimensions	125
8.7. Other Multivariate Optimization Techniques	126
8.8. Subroutine Codes	128
8.9. Problems	133
References	134

List of Subroutines

Chapter 1. Linear Algebra	
Summary of Linear Algebra Commands	X
Chapter 2. Regression	
Single Variable Linear Regression (linreg1)	X
Multivariate Linear Regression (linregn)	X
Polynomial Regression (polyreg)	X
Single Variable Linear Regression with Confidence Intervals (linreg1ci)	X
Chapter 4. Solution of a Single Nonlinear Algebraic Equation	
Successive Approximation (succapp)	X
Bisection (bisect)	X
Single Variable Newton-Raphson (newraph1)	X
Single Variable Newton-Raphson with Numerical Derivatives (nrnd1)	X
Chapter 5. Solution of a System of Nonlinear Algebraic Equations	
Multivariate Newton-Raphson with Numerical derivatives (nrndn)	X
Chapter 6. Numerical Integration	
Trapezoidal Rule (trapezoidal)	X
Simpson's Second Order Method (simpson2)	X
Simpson's Third Order Method (simpson3)	X
Simpson's Fourth Order Method (simpson4)	X
Gaussian Quadrature (gaussquad)	X
Chapter 7. Solution of Ordinary Differential Equations	
Euler Method – 1 Equation IVP (euler1)	X
Runge-Kutta Method – 1 Equation IVP (rk41)	X
Euler Method – n Equations IVP (eulern)	X
Runge-Kutta Method – n Equations IVP (rk4n)	X
Runge-Kutta Method – n Equations BVP (rk4n, byn)	X

Chapter 8. Optimization Bisection Method for optimization – 1 variable (bisect_opt1) X Newton-Raphson Method with numerical derivatives for optimization – 1 variable (nrnd_opt1) X